

# Birkhoff normal forms for betatronic motion and stability indicators

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Celestial and beam dynamics models

Birkhoff normal forms

Dynamic aperture

Lyapunov and noise induced errors

Conclusions

# CELESTIAL MECHANICS

## MODELS

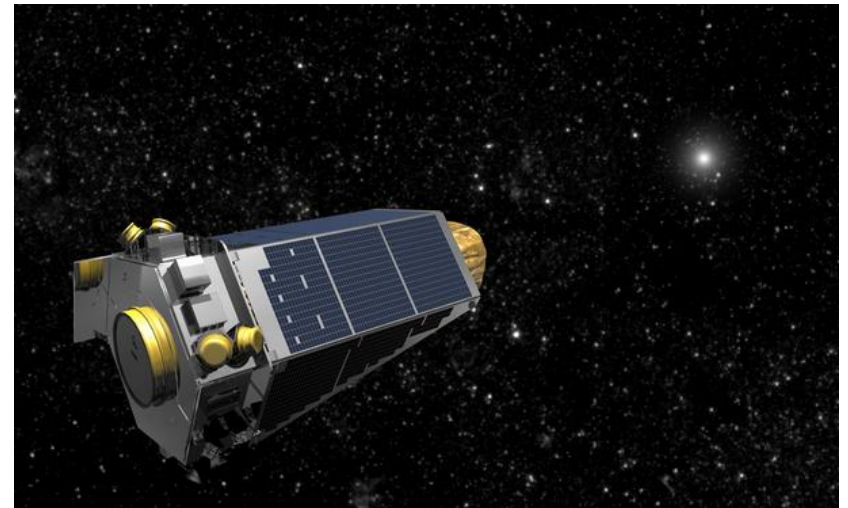
## Fronteers in Physics

Ultimate structure of matter:  
the Higgs boson and beyond

Planetary systems in our  
galaxy, earth like worlds,  
life beyond the earth



Large Hadron Collider



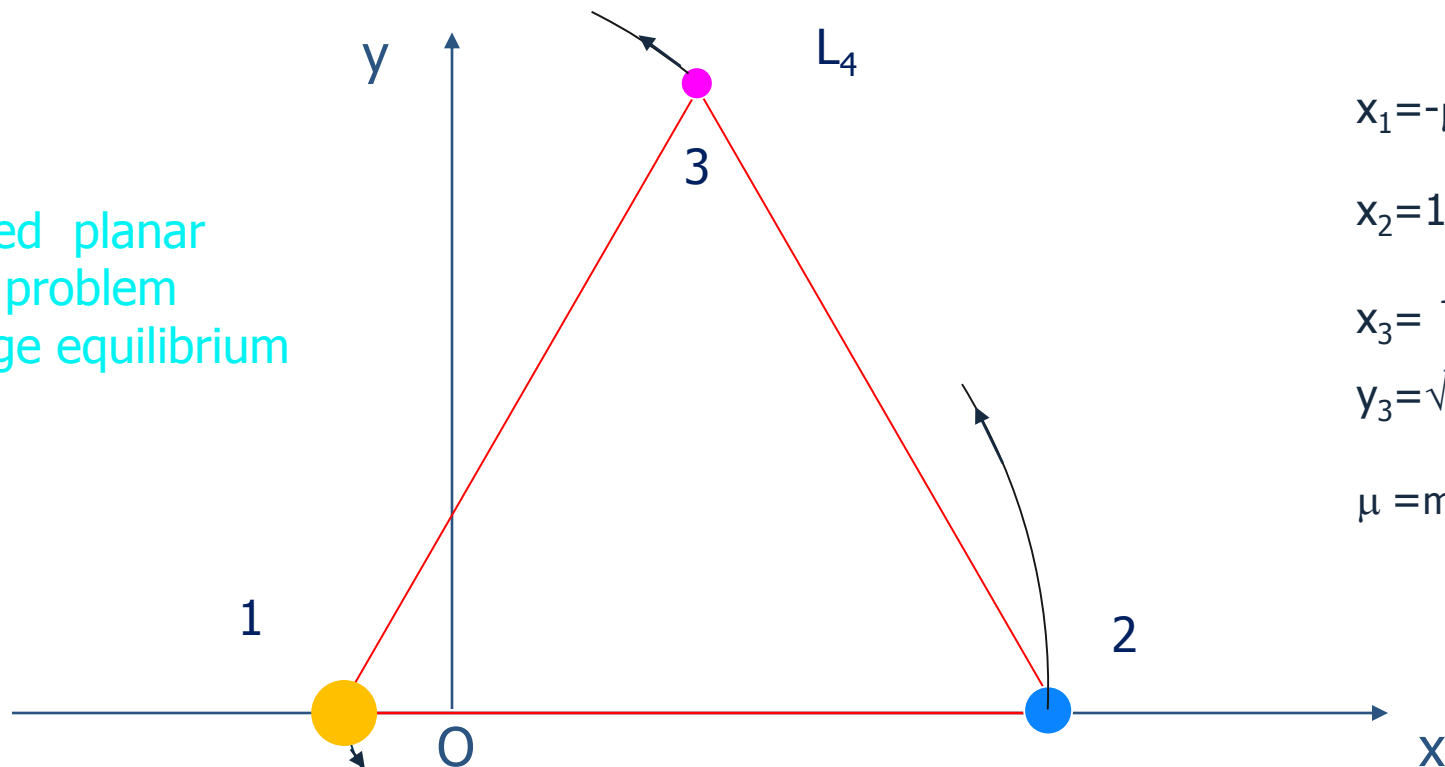
Kepler Space Telescope

## Models in celestial mechanics

A planet in the solar system and of a proton in a ring have dynamical analogies and comparable stability times.

**The 3 body problem:** sun, Jupiter with  $m_1 > m_2$  on circular orbits and a satellite with  $m_3 \rightarrow 0$ . Equilibrium at vertices of an equilateral triangle.

restricted planar  
3 body problem  
Lagrange equilibrium



$$x_1 = -\mu$$

$$x_2 = 1 - \mu$$

$$x_3 = \frac{1}{2} - \mu$$

$$y_3 = \frac{\sqrt{3}}{2}$$

$$\mu = \frac{m_2}{m_1 + m_2}$$

## Birkhoff normal forms for betatronic motion

Scaling coordinates and time ( $r_{12}=1, T=2\pi$ ) the Hamiltonian in **corotating system** where  $V$  is the gravitational potential  $v_x=p_x+y$   $v_y=p_y-x$ .

$$H = \frac{1}{2} (p_x^2 + p_y^2) + yp_x - xp_y + V(x, y)$$

**Normal form** near  $L_4$  where  $X=Y=0$  and  $J_x = \frac{1}{2} (X^2 + P_x^2)$   $J_y = \frac{1}{2} (Y^2 + P_y^2)$

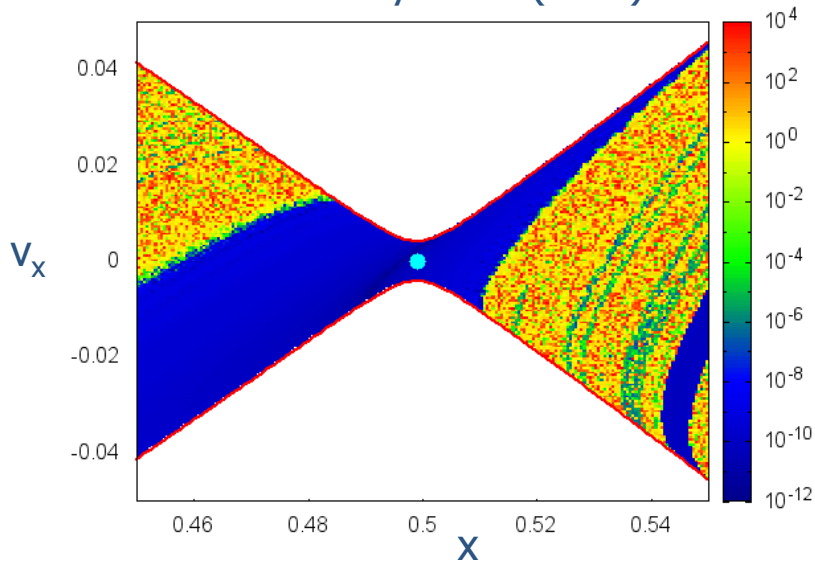
$$H = \omega_1 J_x + \omega_2 J_y + H_3(J_x, J_y) + \dots + R_N \quad \omega_1 \omega_2 < 0$$

$H$  has a **saddle** at  $L_4$  no Lyapunov stability !!

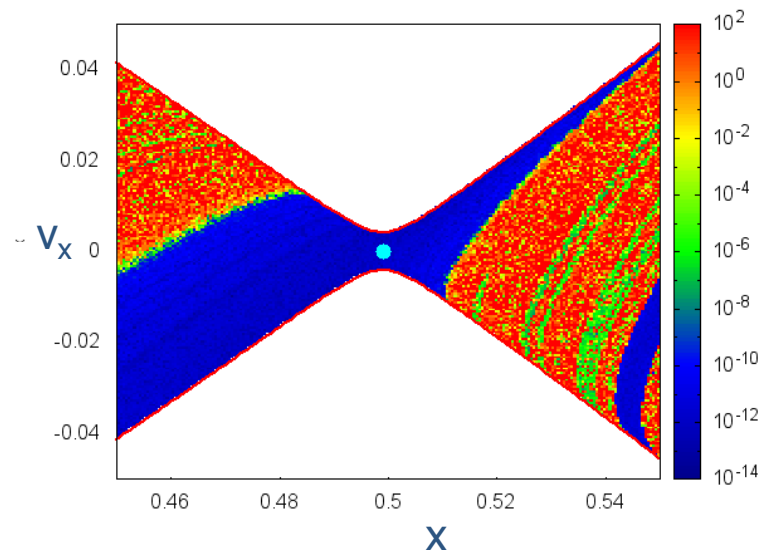
# Birkhoff normal forms for betatronic motion

Error plots. Poincaré section  $y=y_c$   $v_y > 0$   $H=H_c+10^{-5}$   $H_c \sim 1.5$   $t_{\max} = 200 T$

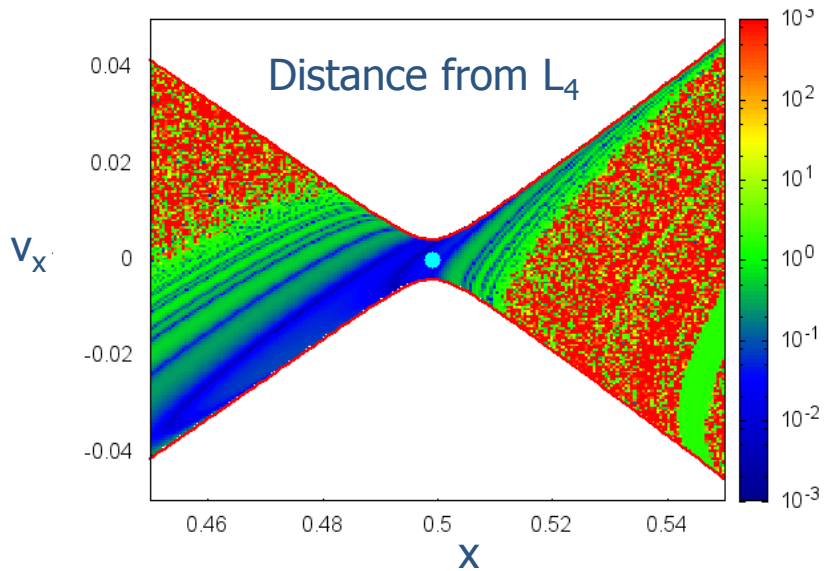
Reversibility error (REM)



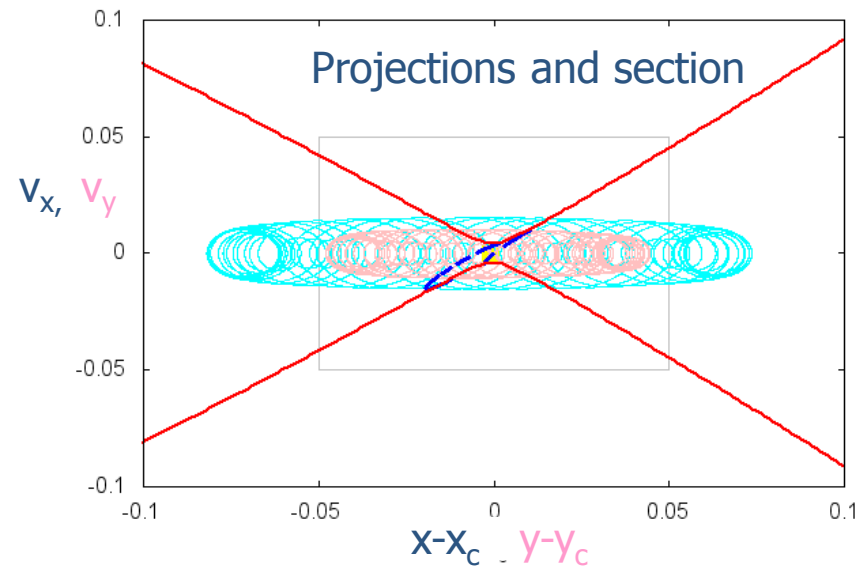
Lyapunov error (LE)



Distance from  $L_4$



Projections and section



## The Hénon-Heiles model.

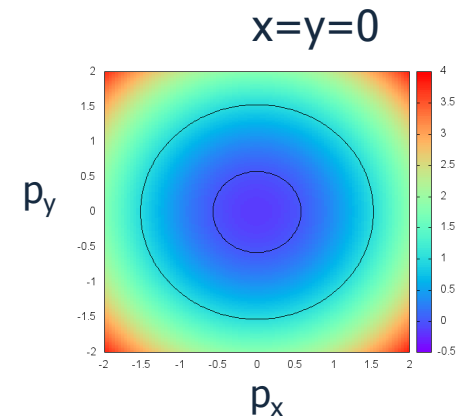
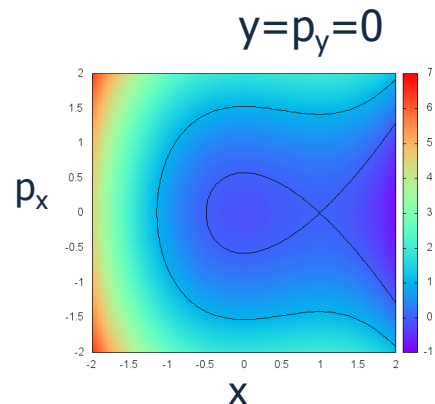
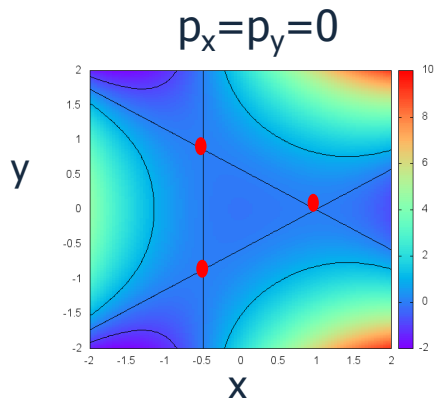
Motion of a star in an elliptical galaxy

$$H = T + V = \frac{1}{2} (p_x^2 + p_y^2) + \frac{1}{2} (x^2 + y^2) - \frac{x^3}{3} + xy^2$$

$V=0$  has a minimum at  $x=y=0$  and three **saddle points** at the vertices of an equilateral triangle where  $V=1/6$

stability  $H < 1/6$

boundary  $H = 1/6$



Isolines of  $H$  : innerst curve  $H=1/6$  stability boundary

# Birkhoff normal forms and betatronic motion

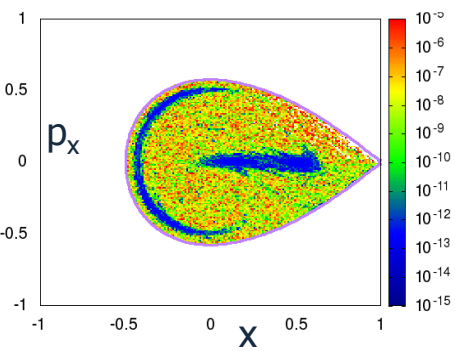
**Error plots** Poincaré section  $y=0$   $p_y > 0$   $H=E$ , boundary  $H(x, p_x, 0, 0)=E$   
 Plots in  $x, p_x$  plane for  $y_0, p_{y0}$  fixed, boundary  $H(x, p_x, y_0, p_{y0})=1/6$   $t_{\max}=20T$

Reversibility error (REM)

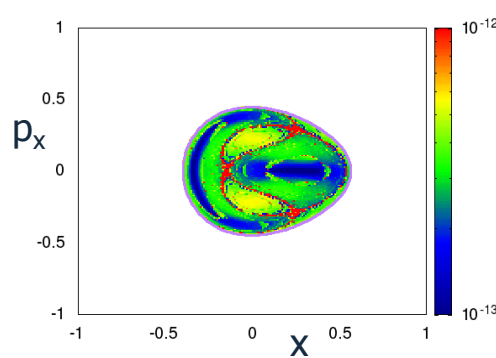
P. section  $y=0$

Orbits

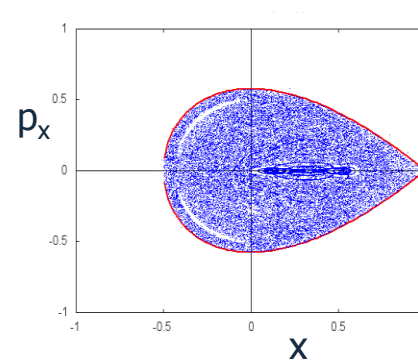
P section  $y=0$



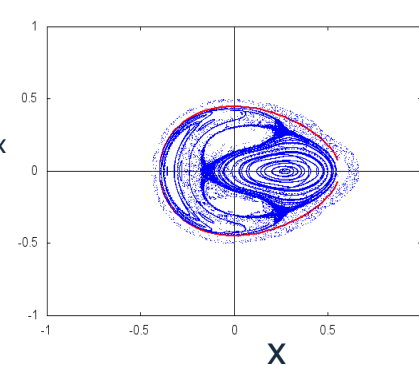
$E=1/6$



$E=0.1$



$E=1/6$



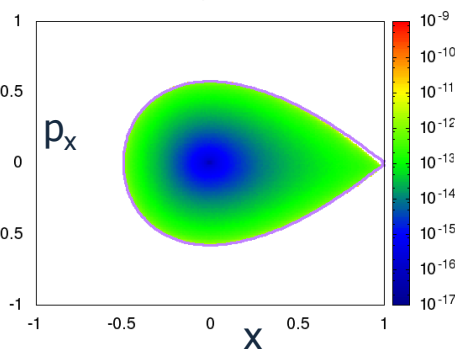
$E=0.1$

REM

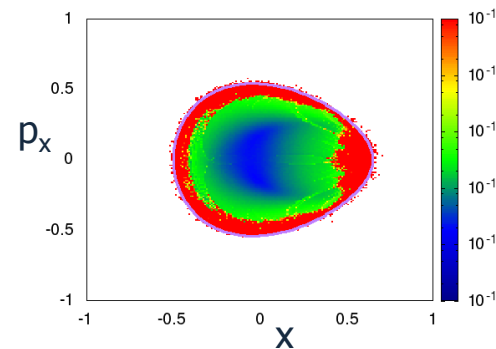
$x, p_x$  plane

H value

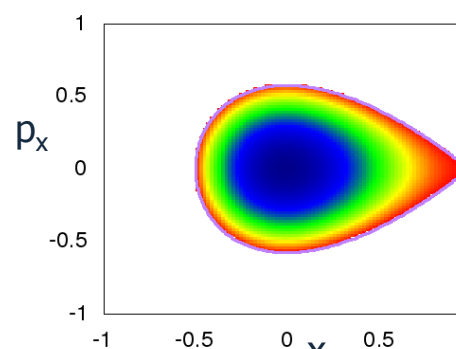
$x, p_x$  plane



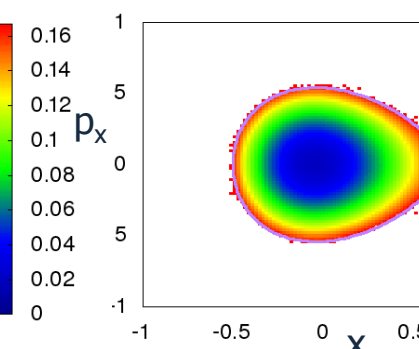
$y_0=p_{y0}=0$



$y_0=p_{y0}=0.2$



$y_0=p_{y0}=0$



$y_0=p_{y0}=0.2$



## Tools for dynamic analysis

- **Normal forms.** Hamiltonian invariant under a symmetry group up to a remainder. Basically an analytic tool.
- **Frequency map error.** The FFT of a quasi periodic signal  $n=2^m$  gives tunes  $\nu=(\nu_1, \nu_2)$ . Error  $e(n) = \| \nu(n) - \nu(n/2) \|$
- **Lyapunov error** . Induced by an initial displacement
- **Reversibility error.** Induced by noise or round-off

# BEAM DYNAMICS

## MODELS

## Beam dynamics models: betatronic motion

Unlike the Kepler problem the circular motion of a charge under a uniform magnetic field  $\mathbf{B}$  is not stable (drift along  $\mathbf{B}$ ).

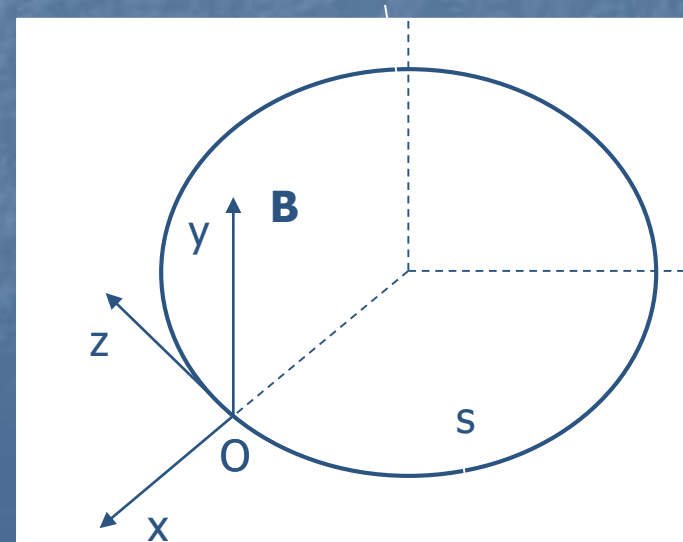
$$H = \frac{1}{2}(p_x^2 + p_y^2) + \frac{1}{2} \frac{x^2}{R^2} + V(x, y, s)$$

$$s = v_0 t \quad p_x = dx/ds$$

Multipoles contribution

$$V = -\frac{1}{2} K_1(s) (x^2 - y^2) - \frac{1}{6} K_2(s) (x^3 - 3xy^2) + \dots$$

Explicit map for thin multipoles  $K_m$  with  $m \geq 3$



# Birkhoff normal forms and betatronic motion

Linear lattice  $M(x) = L x$  conjugated to a rotation

$$L = W R(\omega) W^{-1} \quad W = \begin{pmatrix} \beta^{1/2} & 0 \\ -\alpha \beta^{-1/2} & \beta^{-1/2} \end{pmatrix} \quad \begin{pmatrix} x' \\ p'_x \end{pmatrix} = W_x^{-1} \begin{pmatrix} x \\ p_x \end{pmatrix}$$

← normal form

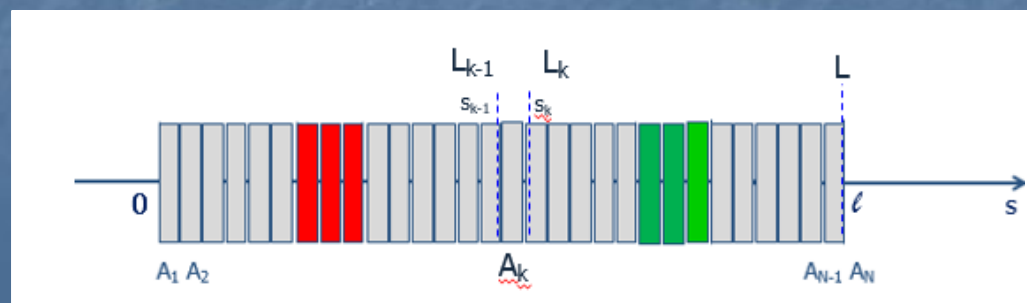
Courant-Snyder coordinates  $x', p'_x$  Change of section from  $s_{k-1}$  to  $s_k$

$$L_k = A_k L_{k-1} A_k^{-1}$$

$$L_k = L(s_k)$$

Exact recurrence for  $\beta_k = \beta(s_k)$ ,

$\alpha_k = \alpha(s_k)$  and phase advance



# Birkhoff normal forms and betatronic motion

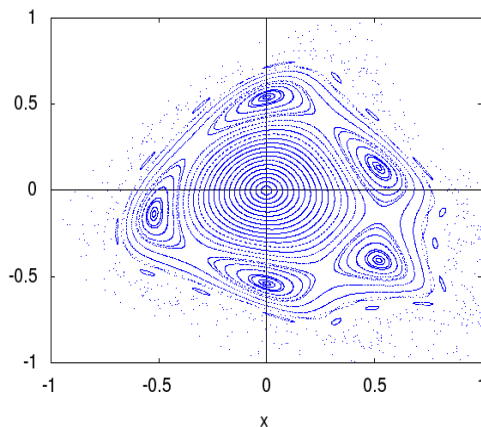
## The 2D Hénon map

One turn map for linear lattice with a thin sextupole in scaled coordinates

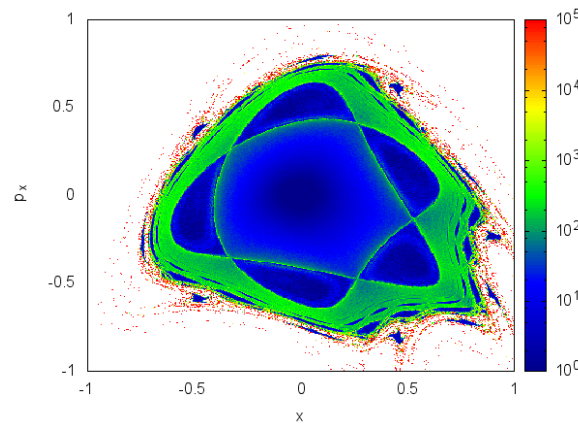
$\mathbf{X} = \frac{1}{2} \beta_x^{3/2} k_2 W^{-1} \mathbf{x}$  for a flat beam

$$\begin{pmatrix} X_{n+1} \\ P_{n+1} \end{pmatrix} = R(\omega) \begin{pmatrix} X_n \\ P_n + X_n^2 \end{pmatrix}$$

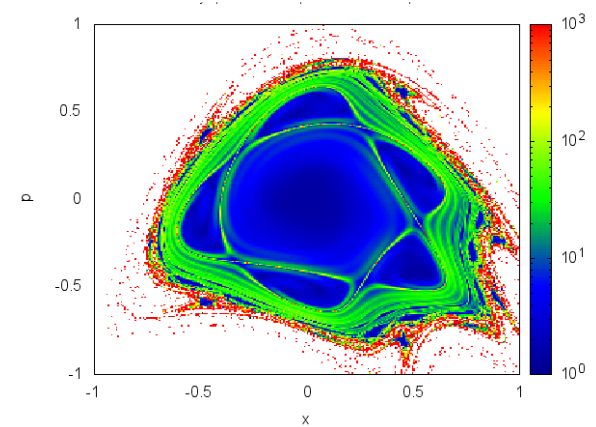
$\nu=0.21$  orbits



normalized REM



Lyapunov error  $N=200$

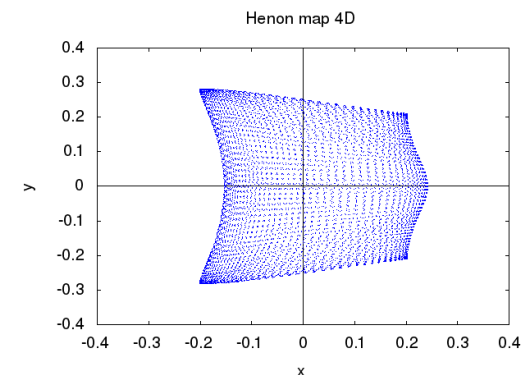
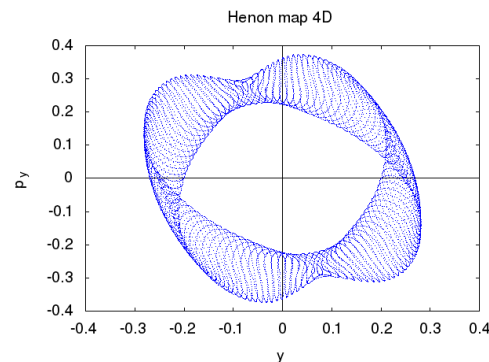
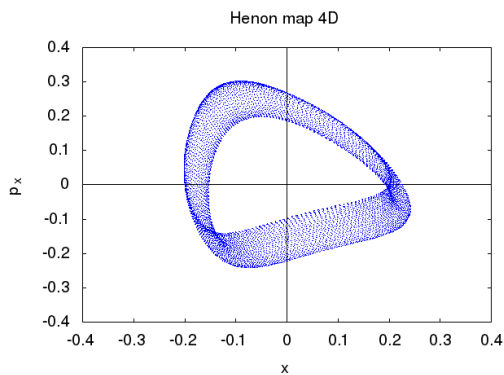


# Birkhoff normal forms and betatronic motion

## The 4D Hénon map

One turn map for a linear lattice with a thin sextupole in scaled coordinates

$$\begin{pmatrix} X_{n+1} \\ P_{x\,n+1} \\ Y_{n+1} \\ P_{y\,n+1} \end{pmatrix} = \begin{pmatrix} R(\omega_x) & 0 \\ 0 & R(\omega_y) \end{pmatrix} \begin{pmatrix} X_n \\ P_{x\,n} + X_n^2 - \beta Y_n^2 \\ Y_n \\ P_{y\,n} - 2\beta X_n Y_n \end{pmatrix} \quad \beta = \frac{\beta_y}{\beta_x}$$



$$v_x = (3 - \sqrt{5})/2$$

$$v_y = \sqrt{2} - 1 \quad \beta = 1$$

projection of orbit with  $x_0 = y_0 = 0.2$   $p_{x0} = p_{y0} = 0$

# BIRKHOFF NORMAL FORMS

## Birkhoff normal forms and betatronic motion

The one turn (superperiod) map  $M$  for thin multipoles is a polynomial which can be truncated to order  $N$ . In Courant-Snyder coordinates

$$M_N(\mathbf{x}) = R(\omega) (\mathbf{x} + P_2(\mathbf{x}) + \dots + P_N(\mathbf{x})) \quad M(\mathbf{x}) = M_N(\mathbf{x}) + O(|\mathbf{x}|^{N+1})$$

A nonlinear symplectic transformation  $\mathbf{x} = \Phi(\mathbf{X})$  changes  $M(\mathbf{x})$  into a new map  $U(\mathbf{X})$  which is invariant under the group generated by  $R(\omega)$

$$M(\mathbf{x}) = \Phi \circ U \circ \Phi^{-1}(\mathbf{x})$$

$$U(R\mathbf{X}) = RU(\mathbf{X})$$

$$U(\mathbf{X}) = R \exp(D_H) \mathbf{X}$$

$$H(R\mathbf{X}) = H(\mathbf{X})$$

$$\Phi(\mathbf{X}) = \exp(D_G) \mathbf{X}$$

$H$  is the **interpolating Hamiltonian**,  $\Phi$  a symplectic coordinates change



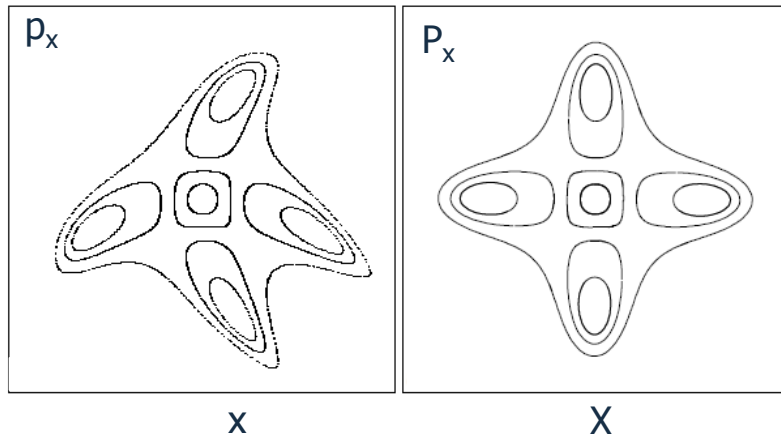
# Birkhoff normal forms and betatronic motion

If  $\omega$  is non resonant ( $\nu = \omega/2\pi$  irrational)  $R(\omega)$  generates a continuous group of rotations  $J = \frac{1}{2}(P_x^2 + X^2)$  is the invariant.

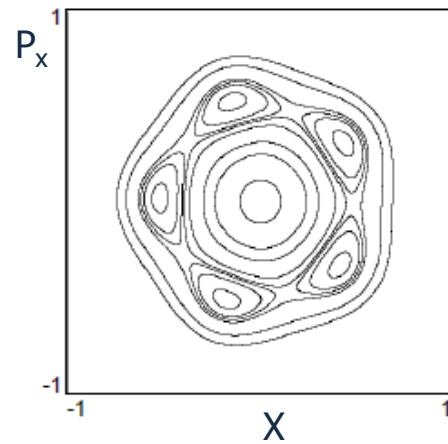
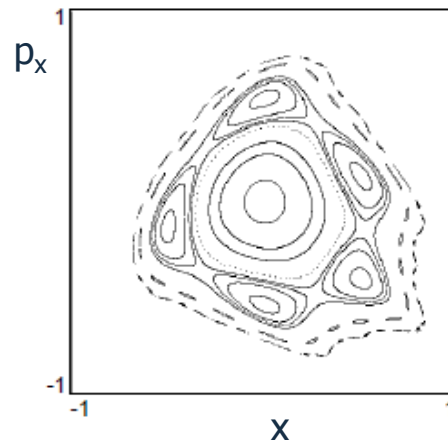
If  $\omega = \omega_R$  is resonant or quasi resonant  $\omega = \omega_R + \varepsilon$  ( $\nu_R = m/q$   $\varepsilon \ll \omega_R$ )  $R(\omega_R)$  generates a discrete group of rotations and

$$H(J, \theta) = \sum_k h_k(J) \cos(k q \theta + \alpha_k)$$

is invariant under the group. The level lines of  $H$  exhibit a chain of  $q$  islands



Quasi resonant normal forms for  $\nu=0.255$  ( $q=4$ ) in  $x, p_x$  and  $X, P_x$  planes



Orbits for  $\nu=0.21$  in  $x, p_x$  plane and quasi resonant normal form ( $q=5$ ) in the  $X, P_x$  plane

## Nekhoroshev stability estimates and analyticity

The series defining the normal forms are divergent due to singularities associated to resonances. Conjugation with normal form up to a remainder

$$M = \Phi_N \circ (U_N + E_N) \circ \Phi_N^{-1} \quad U_N = R \exp(D_{H_N})$$

For a 2D where  $r = (X^2 + P_x^2)^{1/2} = (2J)^{1/2}$  estimate

$$|E_{N-1}| < A (r/r_N)^N \quad r < r_N = 1/(CN)$$

Minimum achieved for  $N = N_* = (e C r)^{-1}$  and  $r/r_{N_*} = e^{-1}$ . In a disc of radius  $r$

$$|E_{N_*}| < A \exp(-N_*) = \exp(-r_*/r) \quad r_* = (eC)^{-1}$$

Orbits starting in a disc  $r/2$  remain in disc of radius  $r$  for  $n|E_{N_*}| < r/2$

$$n < \frac{1}{2} A r \exp(r_*/r)$$

# Birkhoff normal forms and betatronic motion

## Singularities of normalizing transformations

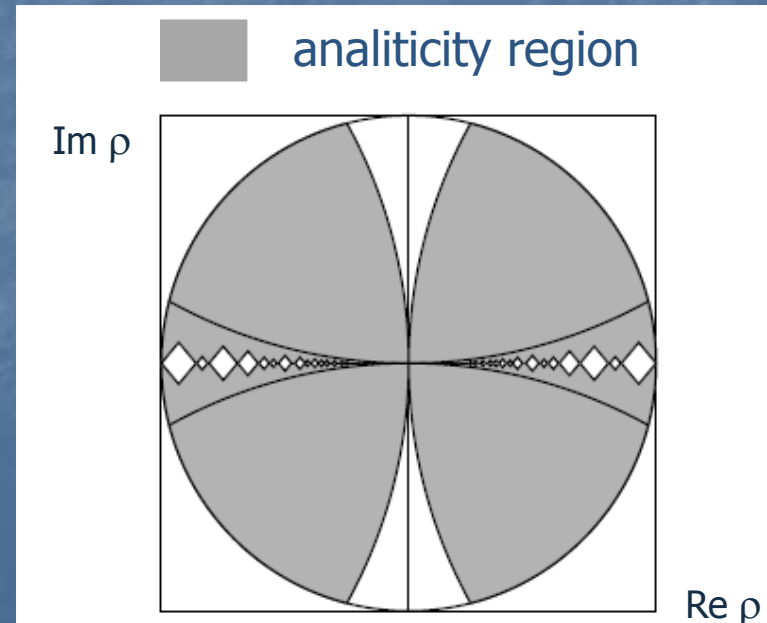
The Birkhoff series diverge due to an accumulation at the origin of the complex  $\rho=2J$  plane of singularities associated to the resonances.

If  $\omega=2\pi p/q + \varepsilon$  for  $\varepsilon \rightarrow 0$  the conjugation function  $\Phi$  behaves as a geometric series.  $\Phi$  has a pole at  $\rho=\rho_q$  where  $\Omega = dH/dJ$  is resonant.

$$\Omega = \omega + \rho \Omega_2 = 2\pi p/q \quad \rightarrow \quad \rho_q = -\varepsilon/\Omega_2$$

In the generic case varying  $\rho$  the frequency crosses infinitely many resonances. The leading ones correspond to the continued fraction expansion  $p_j/q_j$  of the tune  $\nu$  and are located approximately at  $\rho_j = -\varepsilon_j/\Omega_2$  where  $\varepsilon_j = \omega - 2\pi p_j/q_j$

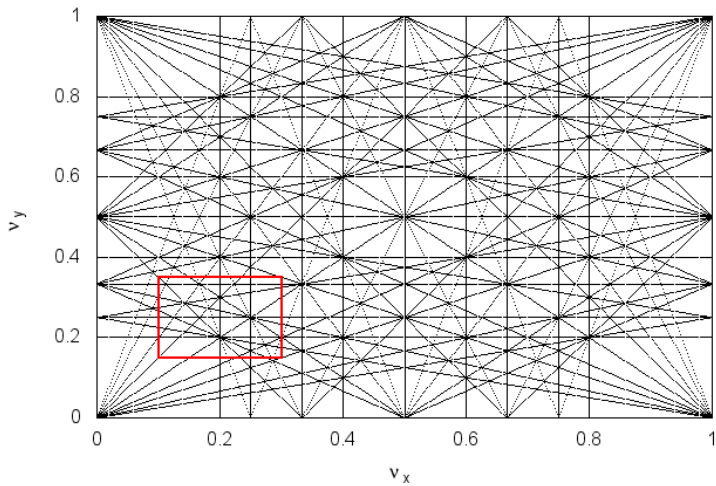
A rigorous analysis confirms this picture. If  $\rho_j > 0$  we have a true resonance (chain of islands). The resonance is virtual if  $\rho_j < 0$



# DYNAMIC APERTURE

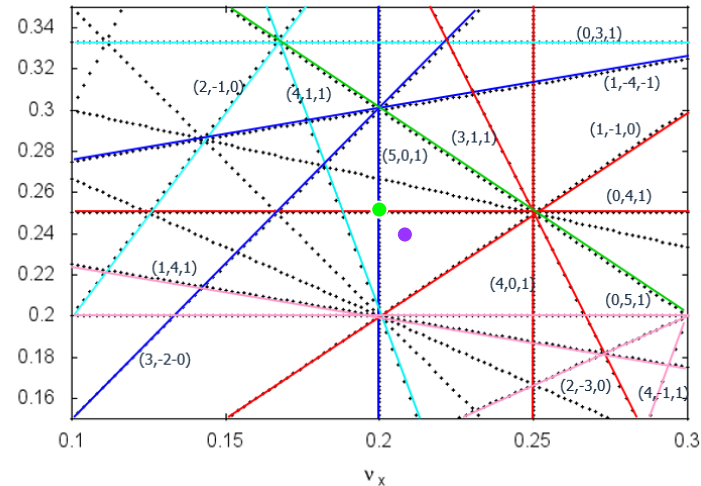
# Birkhoff normal forms and betatronic motion

**Work point.** From  $H = \omega_x J_x + \omega_y J_y + \frac{1}{2}(h_{11} J_x^2 + 2h_{12} J_x J_y + h_{22} J_y^2)$  to any resonance  $k_x \Omega_x + k_y \Omega_y = 2\pi m$  corresponds a line  $a_x J_x + a_y J_y = b$  in action space

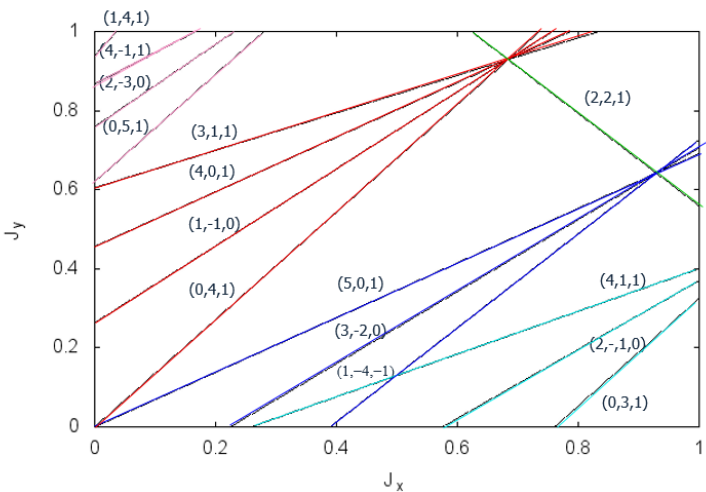


Tune plot

$$|k_x| + |k_y| \leq 5$$



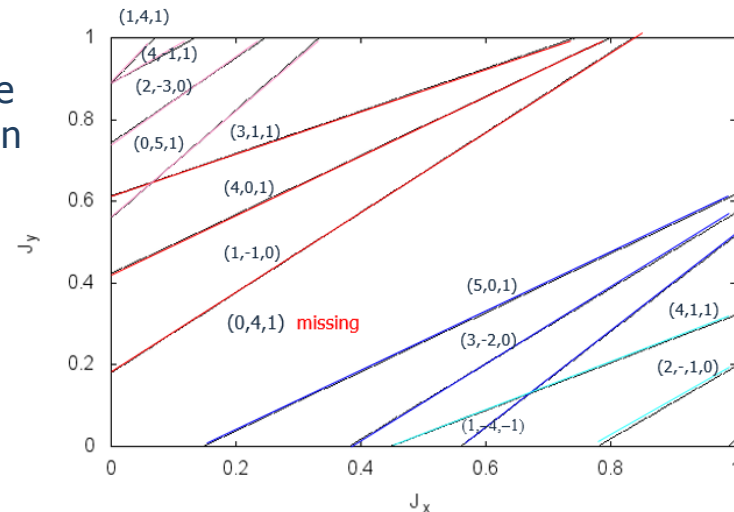
Tune plot  
magnif.



Resonance  
lines action  
space

$$v_x = 1/5$$

$$v_y = 1/4$$



Resonance  
lines action  
space

$$v_x = 0.21$$

$$v_y = 0.19$$



# Birkhoff normal forms and betatronic motion

## Short term dynamic aperture of 2D Hénon map

Boundary of stability domain of  $H$  for unstable resonances.

**Resonance 0:** as  $\omega \rightarrow 0$  interpolating Hamiltonian  $H = \frac{1}{2} \omega (P^2 + X^2) - X^3/3$

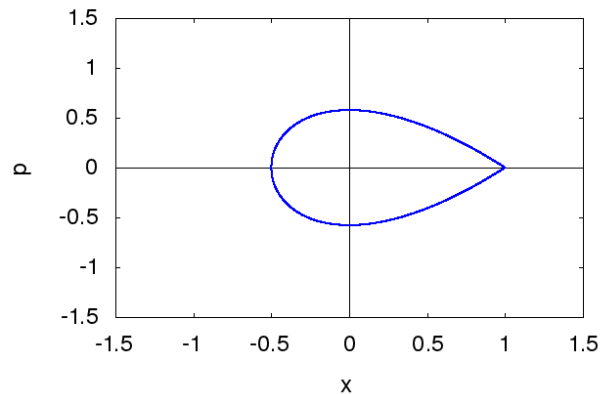
Scaling  $X = \omega x, P = \omega p$  and  $H = \omega^3 h$  boundary  $h = 1/6$

$$h - \frac{1}{6} = \frac{p^2}{2} - \frac{1}{6} (1-x)^2 (1+2x) = 0$$

**Resonance 1/3:** as  $\varepsilon = \omega - 2\pi/3 \rightarrow 0$  interpolating Hamiltonian

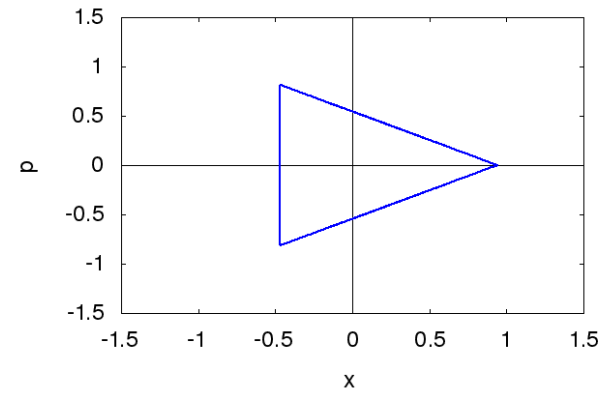
$$H = \varepsilon J - 4 J^{3/2} \cos(3\theta)$$

$\nu \rightarrow 0$



Dynamic aperture  
of Hénon map  
from resonant  
normal forms

$\nu - 1/3 \rightarrow 0$



# Birkhoff normal forms and betatronic motion

At the critical saddle points of  $h = 4/27$  After a scaling with  $\varepsilon$

$$h - \frac{4}{27} = \frac{1}{2} \left( 1 + \frac{3x}{\sqrt{2}} \right) \left( p^2 - \frac{1}{3} \left( x - \frac{2\sqrt{2}}{3} \right)^2 \right) \leq 0$$

## Short term dynamic aperture of 4D Hénon map

For  $\omega_1 = \omega_2 = \omega \rightarrow 0$  after scaling  $X = \omega x, \dots, P_y = \omega p_y$  and  $H = \omega^3 h$  where  $h$  is Hénon-Heiles hamiltonian

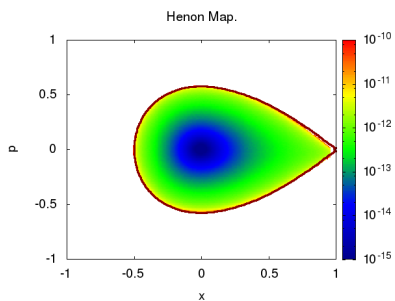
$$h - \frac{1}{6} = \frac{p_x^2 + p_y^2}{2} + \frac{1}{6} (1 + 2x) (3y^2 - (1-x)^2) = 0$$

stability region  $h < 1/6$

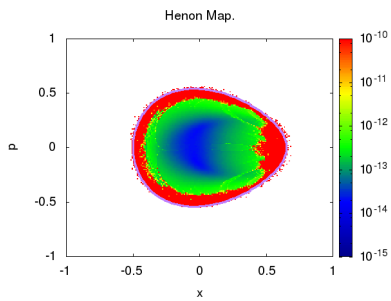
boundary  $h = 1/6$

# Birkhoff normal forms and betatronic motion

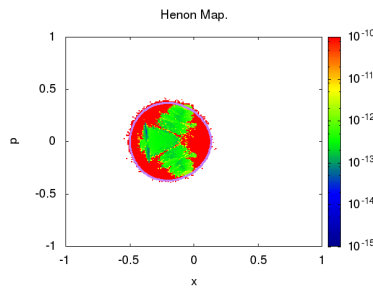
Dynamic aperture and REM error plots for  $v_x = v_y = 0.01$  Iterations  $n=5000$   
 Plots in  $x, p_x$   $y, p_y$  and  $x, y$  planes. Coordinates scaled by  $\omega = 2\pi v_x$



$p_y=0$   $y=0$



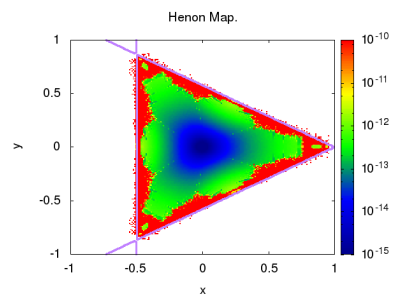
$y=0.2$



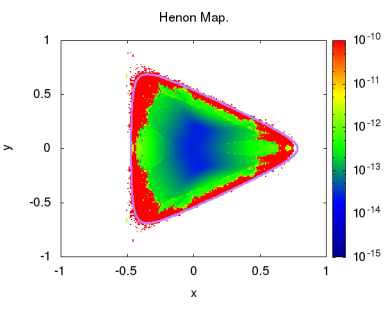
$y=0.5$

$x$   $p_x$  plane

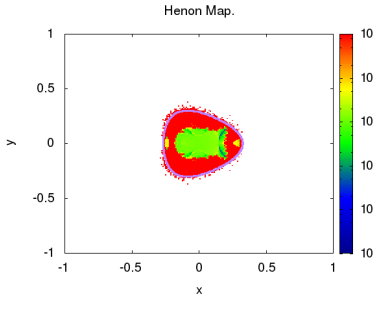
purple curve  
analytic boundary



$p_y=0$   $p_x=0$



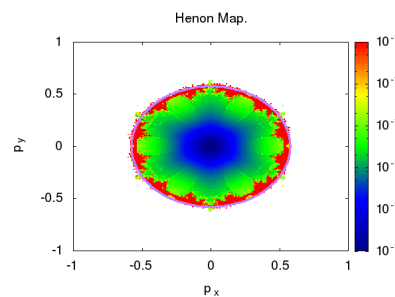
$p_x=0.2$



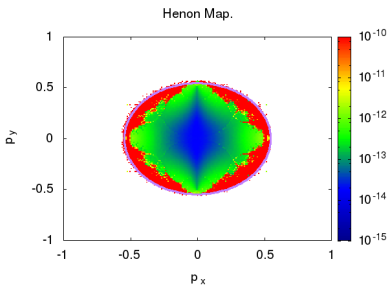
$p_x=0.5$

$x$   $y$  plane

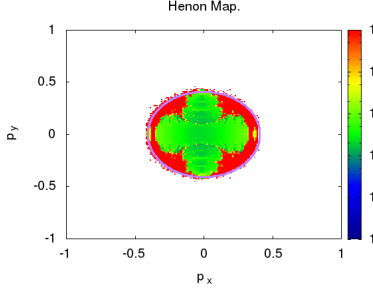
Iterations 5000



$p_x=0$   $x=0$



$x=0.2$



$x=0.5$

$y$   $p_y$  plane

coordinates scaled by  $\omega$



# LYAPUNOV AND NOISE ERRORS

# Birkhoff normal forms and betatronic motion

Errors due to a small displacement or small noise allow **stability** assessments

## Lyapunov error LE

Small initial displacement: let iterates of  $\mathbf{x}_0$  and  $\mathbf{x}_0 + \varepsilon \boldsymbol{\eta}$   $\|\boldsymbol{\eta}\|=1$  be  $\mathbf{x}_n$  and  $\mathbf{x}_n + \varepsilon \boldsymbol{\eta}_n + O(\varepsilon^2)$  **Normalized Lyapunov error**

$$e_L(n, \boldsymbol{\eta}) = \|\boldsymbol{\eta}_n\|$$

$$\boldsymbol{\eta}_n = DM(\mathbf{x}_{n-1}) \boldsymbol{\eta}_{n-1}$$

or

$$e_L(n, \boldsymbol{\eta}) = \|A_n \boldsymbol{\eta}\|$$

$$A_n = DM^n(\mathbf{x}_0)$$

DM denotes the tangent map. To have a result independent from the vector  $\boldsymbol{\eta}$  we sum over the errors for any orthonormal basis obtaining

$$e_L(n) = (\text{Tr}(A_n^T A_n))^{1/2}$$

# Birkhoff normal forms and betatronic motion

## Forward error FE

Noise of vanishingly small amplitude:  $\xi_n$  a random vector  $\langle \xi_n \xi_m^T \rangle = I \delta_{nm}$

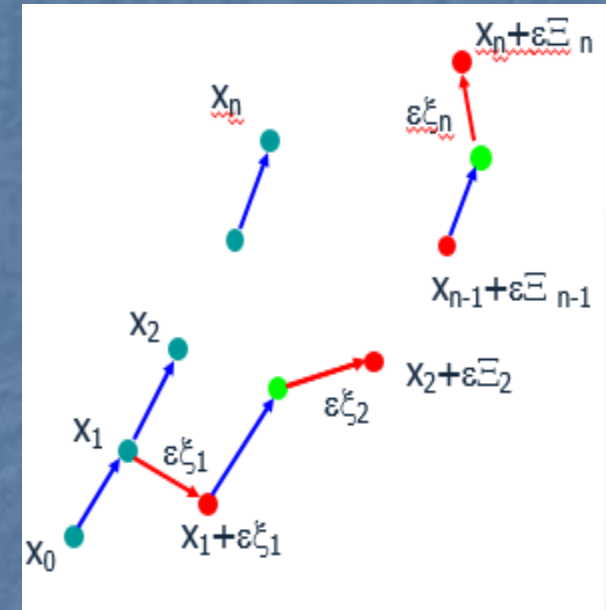
$$\mathbf{x}_{\varepsilon,n} = M(\mathbf{x}_{\varepsilon,n-1}) + \varepsilon \xi_n = \mathbf{x}_n + \varepsilon \Xi_n + O(\varepsilon^2)$$

Global stochastic perturbation

$$\Xi_n = \lim_{\varepsilon \rightarrow 0} \frac{\mathbf{x}_{\varepsilon,n} - \mathbf{x}_0}{\varepsilon}$$

non homogeneous recurrence

$$\Xi_n = DM(\mathbf{x}_{n-1}) \Xi_{n-1} + \xi_n \quad \Xi_0 = 0$$



The normalized forward error is defined by

$$e_F(n) = \langle \Xi_n \cdot \Xi_n \rangle^{1/2} = \left( \sum_{k=0}^{n-1} \text{Tr}(B_k(n) B_k^T(n)) \right)^{1/2} \quad B_k(n) = DM^k(\mathbf{x}_{n-k})$$

Notice  $e_F^2(n)$  is the trace of covariance matrix  $\langle \Xi_n \Xi_n^T \rangle$

## Reversibility error RE

with respect to the initial condition after  $n$  iterations forward and backwards with noise. Let  $\mathbf{x}_{\varepsilon, -m, n}$  be the error after  $n$  iterations with  $M$  and  $m$  with  $M^{-1}$

$$\mathbf{x}_{\varepsilon, -m, n} = M^{-1}(\mathbf{x}_{\varepsilon, -m+1, n}) + \varepsilon \xi_{-m} = \mathbf{x}_{n-m} + \varepsilon \Xi_{-m, n} + O(\varepsilon^2)$$

Global stochastic process

$$\Xi_n^R = \lim_{\varepsilon \rightarrow 0} \frac{\mathbf{x}_{\varepsilon, -n, n} - \mathbf{x}_n}{\varepsilon} = \Xi_n + \sum_{k=0}^{n-1} DM^{-k}(\mathbf{x}_k) \xi_{-(n-k)}$$

Error is defined by

$$e_R(n) = \langle \Xi_n^R \cdot \Xi_n^R \rangle^{1/2} = \left( \sum_{k=0}^{n-1} \text{Tr}(C_k(n)C_k^T(n)) + \sum_{k=0}^{n-1} \text{Tr}(AI_k(n)AI_k^T(n)) \right)^{1/2}$$

where  $AI_k = DM^{-k}(\mathbf{x}_k)$  and  $C_k = AI_n B_k$

# Birkhoff normal forms and betatronic motion

## Linear maps

Errors asymptotics elementary for linear maps  $DM(\mathbf{x}) = L \mathbf{x}$

$$e_L(n) = \left( \text{Tr} \left( (L^n)^T L^n \right) \right)^{1/2} \quad e_F(n) = \left( \sum_{k=0}^{n-1} e_L^2(k) \right)^{1/2}$$

- elliptic fixed point

$$e(n) \sim 1 \quad \text{for LE} \quad e(n) \sim n^{1/2} \quad \text{for FE, RE}$$

- parabolic f. p.

$$e(n) \sim n \quad \text{for LE} \quad e(n) \sim n^{3/2} \quad \text{for FE, RE}$$

- hyperbolic f. p.

$$e(n) \sim e^{\lambda n} \quad \text{for LE, FE, RE}$$

# Birkhoff normal forms and betatronic motion

## Power law growth and oscillations

Rotation:

$$L=R(\omega) \quad e_L(n)=\sqrt{2} \quad e_F(n)=(2n)^{1/2}$$

$$L = \Phi R(\omega) \Phi^{-1} \quad e_L(n) = (A - (A-2) \cos(2n\omega))^{1/2} \quad A \geq 2 \quad e_L(n) \text{ oscillates}$$

Integrable map in normal form  $M(\mathbf{x}) = R(\Omega(\|\mathbf{x}\|^2/2)) \mathbf{x}$

$$e_L^2(n) = 2 + (\Omega' \|\mathbf{x}\|^2)^2 n^2$$

$$e_F(n) \sim n^{3/2} \quad e_R(n) = e_F(2n)$$

Integrable map not in normal form  $M = \Phi R(\Omega) \Phi^{-1}$  power law error growth with oscillations.

# Birkhoff normal forms and betatronic motion

## Averaging on oscillations

Local error growth rate given by

$$De(n) = \frac{d \log e(n)}{d \log n} \quad n \in \mathbb{R}$$

$$De(n) = \frac{\log e(n+1) - \log e(n)}{\log(n+1) - \log n} \quad n \in \mathbb{N}$$

$$D n^\alpha = \alpha$$

$$D e^{\lambda n} = \lambda n \quad n \in \mathbb{R}.$$

To damp oscillations of  $De(n)$  double average was proposed

$$Y(n) = 2 \langle\langle D e \rangle\rangle(n)$$

$Y(n)$  is the **mean exponential growth factor of nearby orbits** (MEGNO),  
Cincotta et al (2001)

In the next slides we compare the errors for the 2D Hénon map

**LE** normalized Lyapunov error  $e_L(n)$ . The error  $e_L(n, \eta)$  is avoided since  $\eta$  introduces a bias.

**FE** and **RE** The exact formulae involve the tangent map

**REM** reversibility error (method) due to round off.

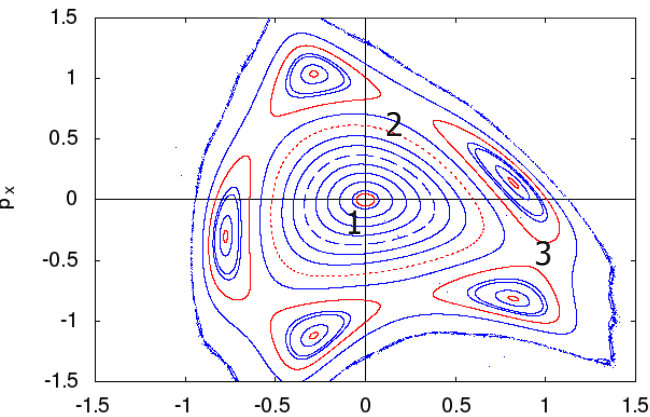
The computation of **REM** requires just  $n$  iterates of the map followed by  $n$  iterates of the inverse map. One can avoid the tangent map in computing **LE** choosing  $\varepsilon=10^{-14}$  and two orthonormal vectors  $\eta$



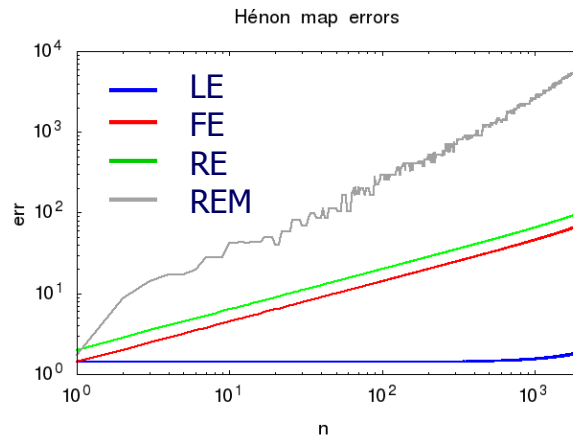
# Birkhoff normal forms and betatronic motion

Power law growth of  $e(n)$  for Hénon map

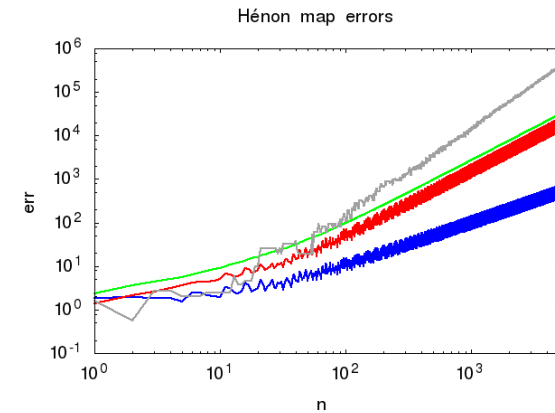
orbits  $v = \sqrt{2} - 1$



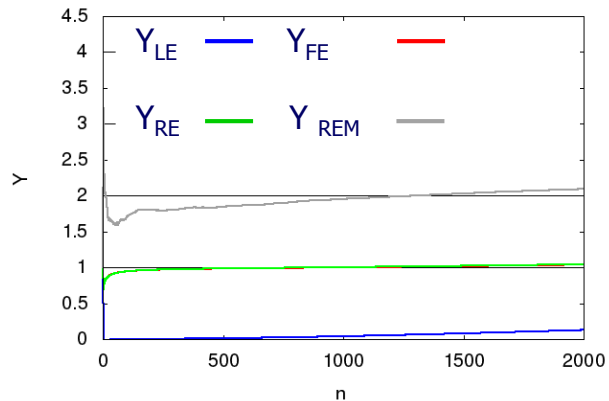
errors 1:  $x_0=0.05$   $p_0=0$



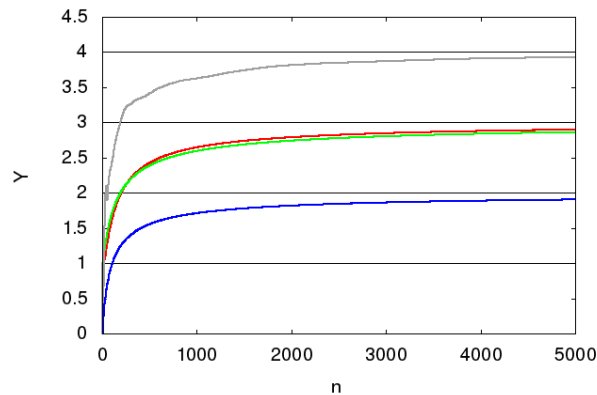
2:  $x_0=0.6$   $p_0=0$



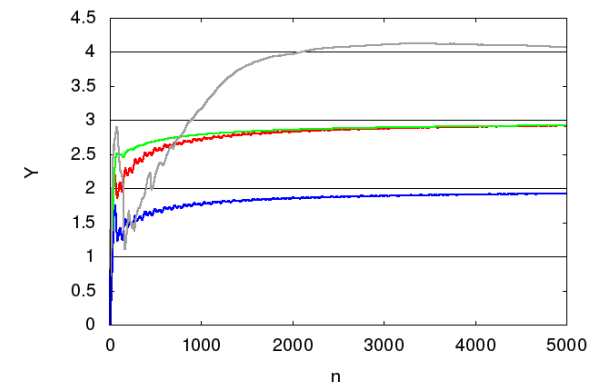
averages 1:  $x_0=0.05$   $p_0=0$



2:  $x_0=0.6$   $p_0=0$



3:  $x_0=0.75$   $p_0=0$

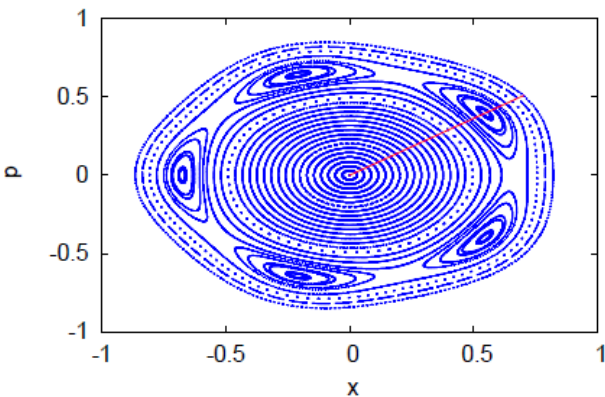


# Birkhoff normal forms and betatronic motion

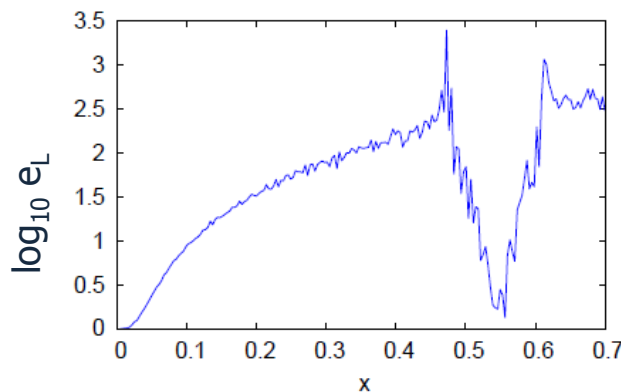
**Integrable map.** Near a stable resonance  $\nu = m/q + \varepsilon/2\pi$  with  $q > 4$  the resonant normal form gives a good approximation up to the dynamic aperture.

$$H(x, p) = \frac{\Omega_2}{2} \left( J + \frac{\epsilon}{\Omega_2} \right)^2 + J^{q/2} \left( A + B T_q \left( \frac{x}{\sqrt{2J}} \right) \right)$$

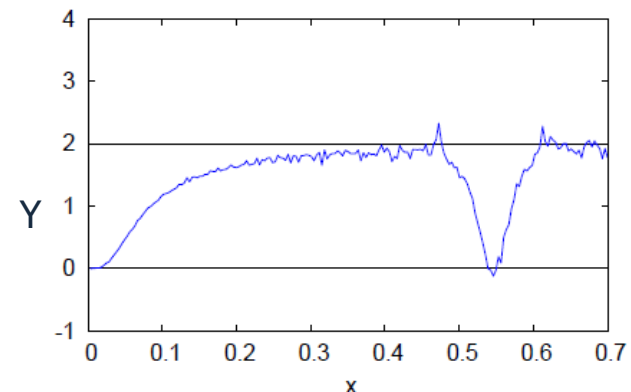
The errors growth follow a power law  $e_L(n) \sim n |\Omega'(J)| J$ . Near the separatrix  $\Omega(J) \sim 1/\log(J_s - J)$  and  $\Omega' \sim (J_s - J)^{-1}$  still a power law



Orbits of  $H$  near  $1/5$  resonance



Lyapunov error  $e_L(n)$



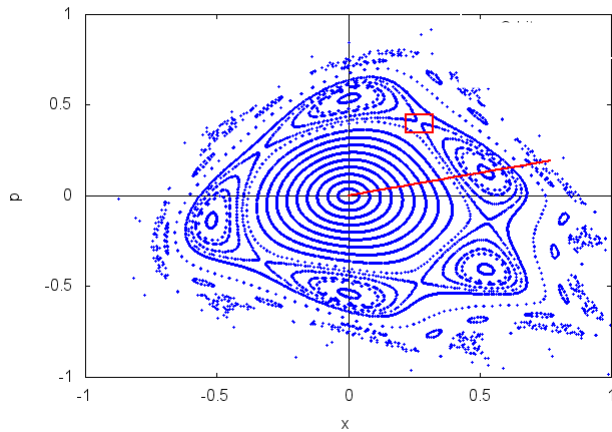
MEGNO average  $Y_L(n)$

$$\mathbf{x}_n = \exp(n \Delta t D_H) \mathbf{x}_0 \quad \text{with } \Delta t = 0.2 \quad n = 1000$$

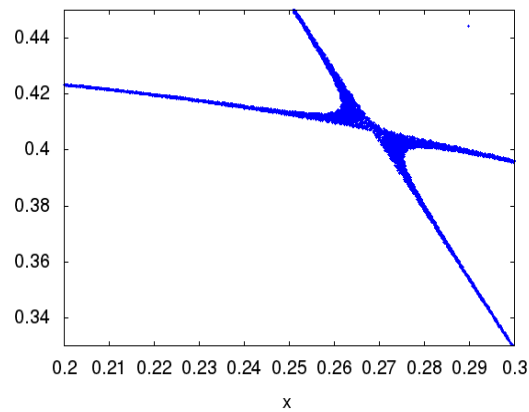
# Birkhoff normal forms and betatronic motion

For the Hénon map the boundary of a chain of islands is a chaotic layer, where the errors growth is **exponential**. Plots for  $e(n)$ ,  $Y(n)$  when  $\nu=0.21$

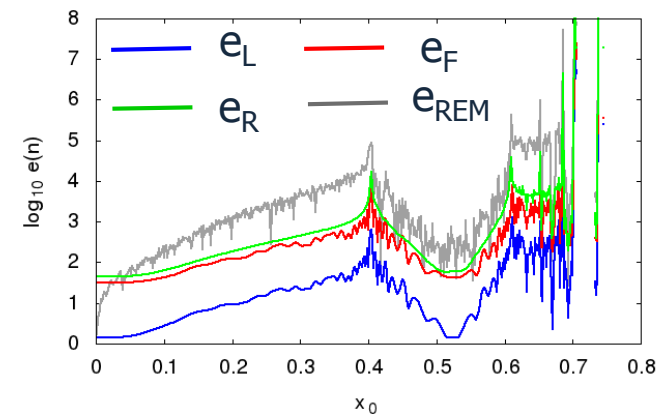
Obits



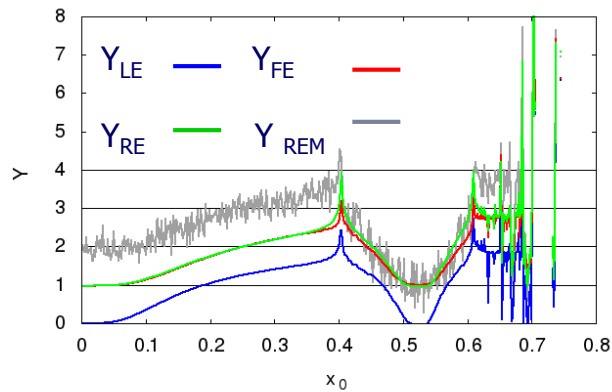
magnification



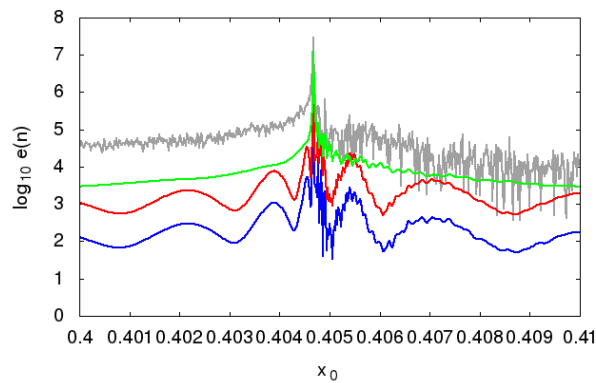
errors  $\log_{10} e(n)$



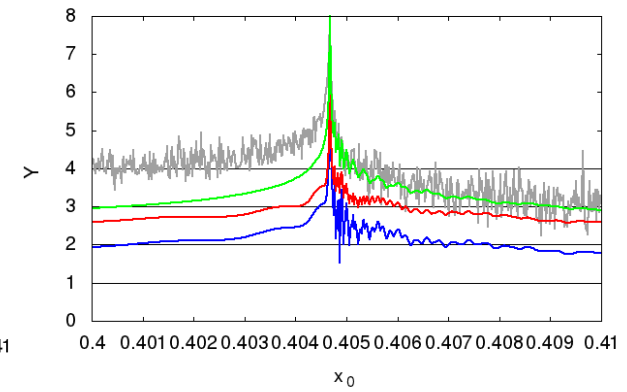
averages  $Y(n)$



errors zoom



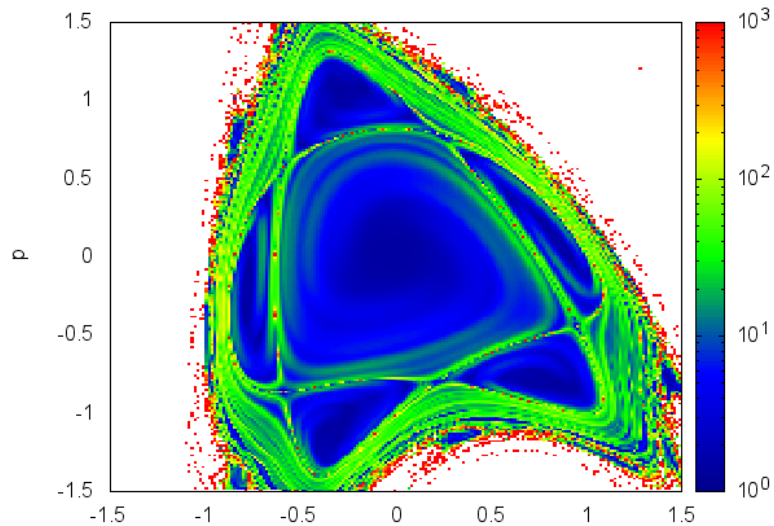
averages  $Y(n)$  zoom



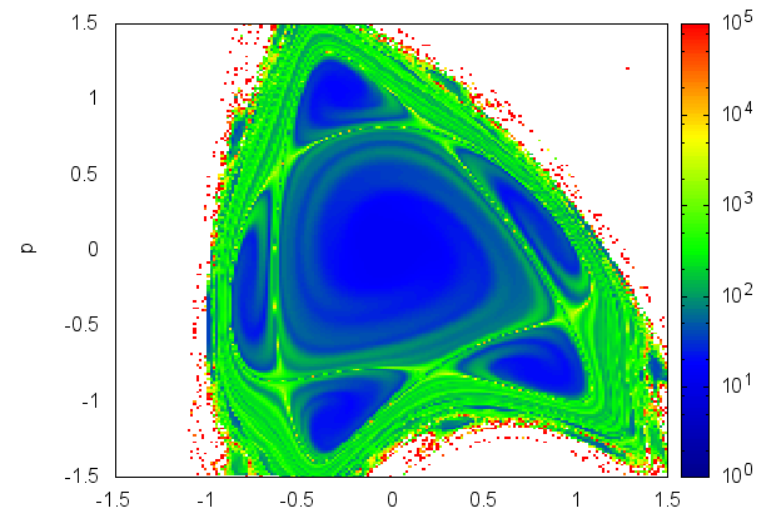
# Birkhoff normal forms and betatronic motion

Normalized REM error color plots for  $\nu = \sqrt{2} - 1$   $N=100$

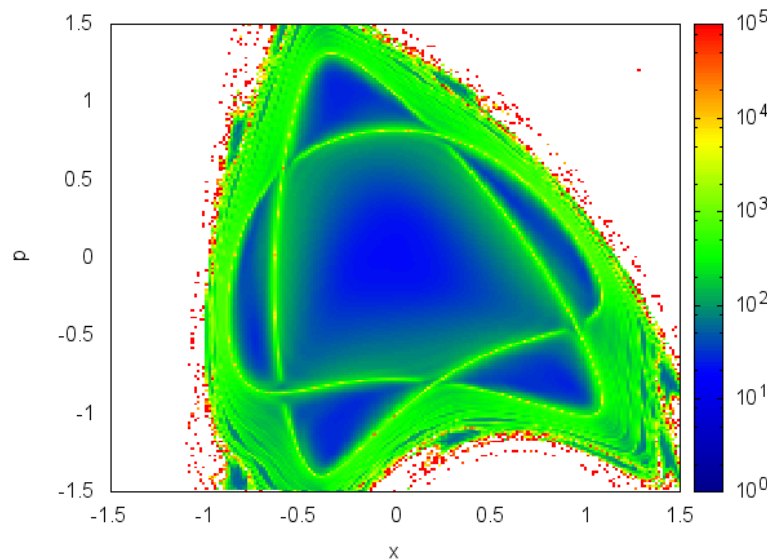
LE



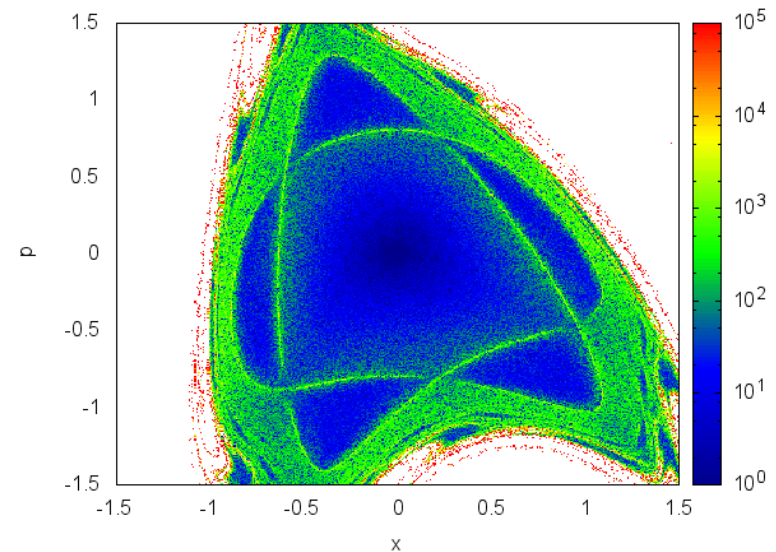
FE



RE



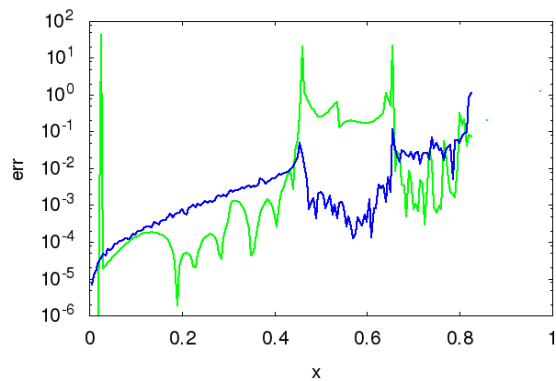
RE round off



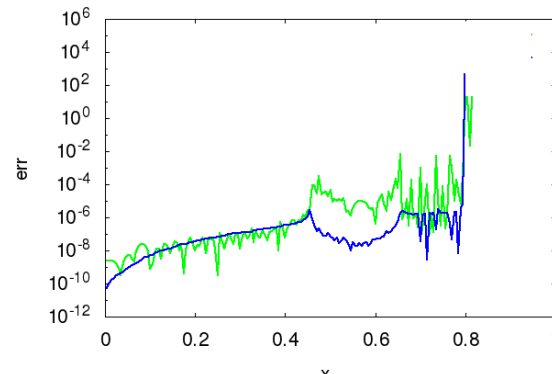
# Birkhoff normal forms and betatronic motion

## Comparison of frequency map error and REM

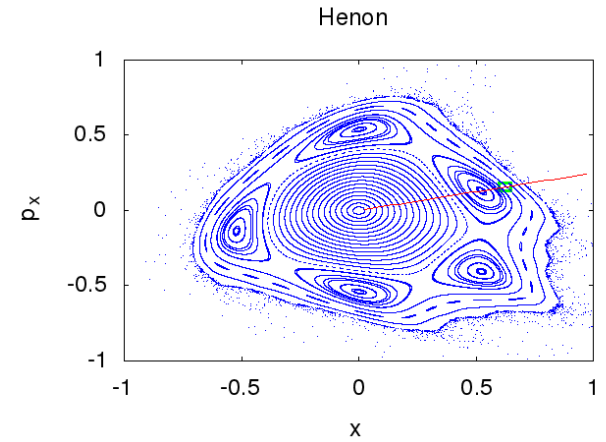
— Frequency map error      — REM



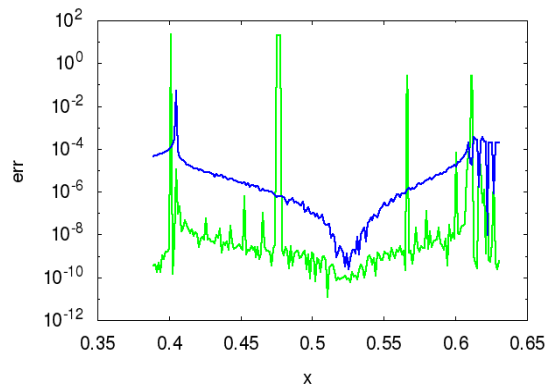
$n=2^{11}$



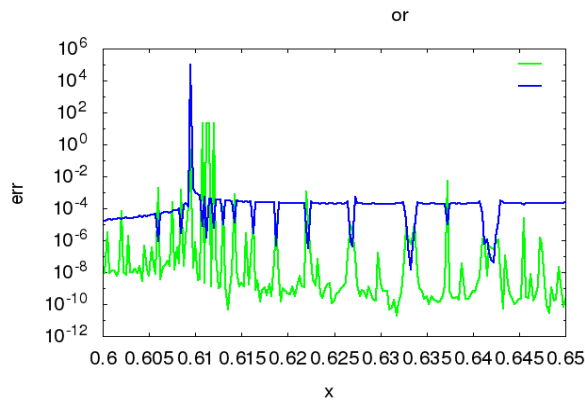
$n=2^{14}$



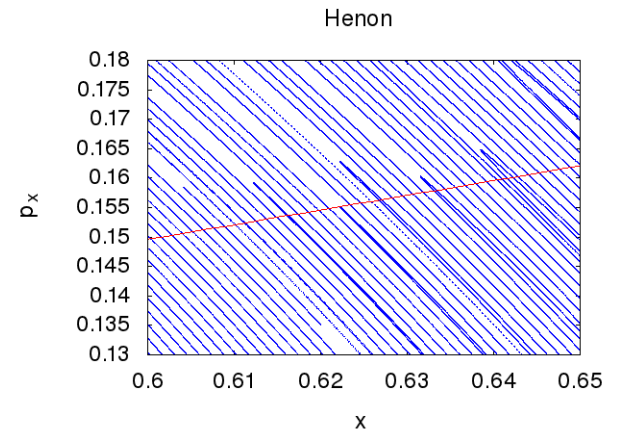
Henon



$n=2^{14}$



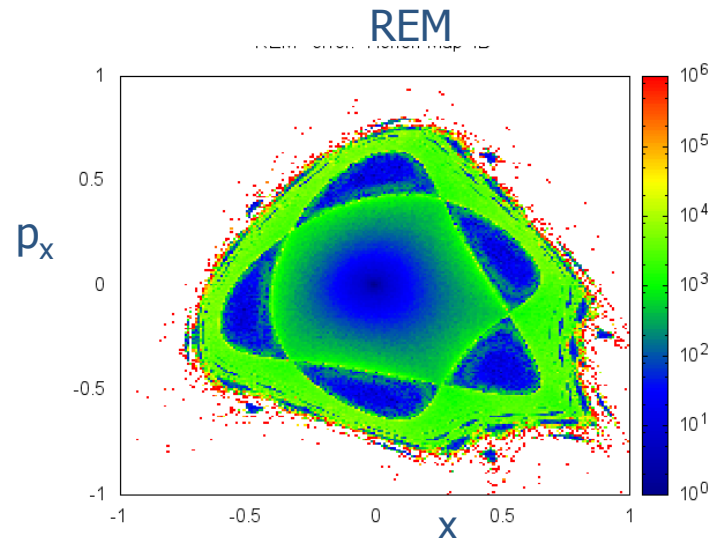
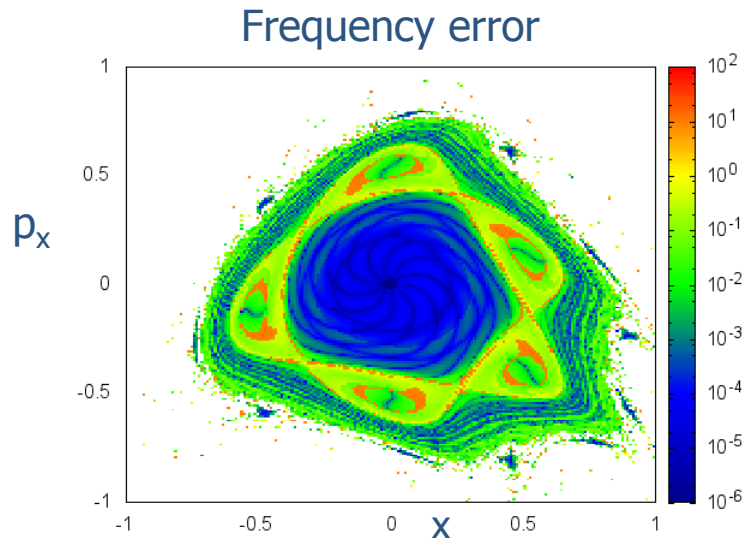
$n=2^{14}$



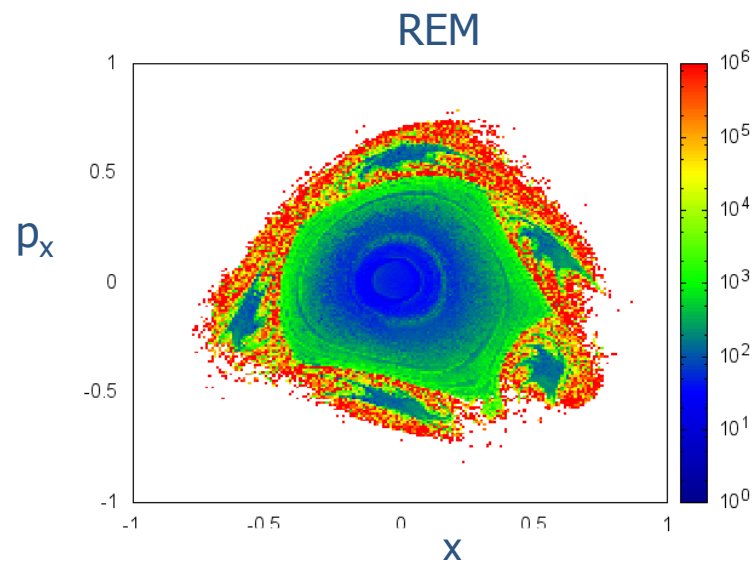
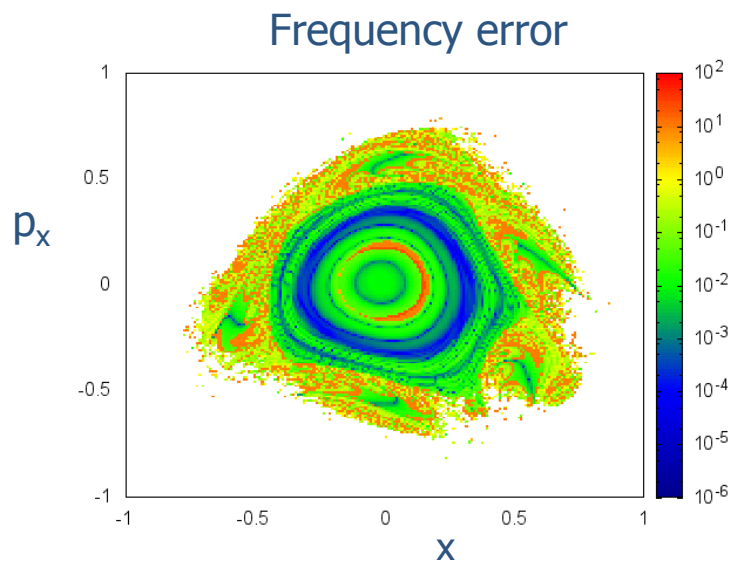
Henon

# Birkhoff normal forms and betatronic motion

Frequency error and REM: 4D Hénon map tunes  $\nu_1=0.21$   $\nu_2=0.25$   
 $x, p_x$  plane



$y_0=p_{y0}=0$



$y_0=0.15$

$p_{y0}=0$

# CONCLUSIONS

# Birkhoff normal forms and betatronic motion

Beam and celestial dynamics share the same tools

- The **Birkhoff normal forms** describe the non linear betatron motion
- Resonance induced singularities make the series asymptotic
- Applications: tune diagrams, dynamic aperture, slow extraction
  
- The Lyapunov and noise induced **errors** provide stability portraits
- The round off **reversibility** error gives comparable results
- The error analysis applies in absence of a first integrals  $H$



## REFERENCES

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- [2] A Bazzani, M Giovannozzi, G Servizi, E Todesco, G Turchetti. *Resonant normal forms, interpolating Hamiltonians and stability analysis of area preserving maps*. Physica D: Nonlinear Phenomena, **64**, 66, (1993).
- [3] A. Bazzani, E. Todesco, G. Turchetti, G. Servizi *A normal form approach to the theory of nonlinear betatronic motion* CERN Yellow Reports 94-02 (1994)  
<http://cds.cern.ch/record/262179/files/CERN-94-02.pdf>
- [4] F. Panichi, L. Ciotti, G. Turchetti Fidelity and reversibility in the restricted 3 body problem Communications in Nonlinear Science and Numerical Simulation **35** , 53-68 (2015)